# Non-contacting two-channel speed sensor type FA5 with aluminium flange housing and stainless steel sensor tube

Scanning type	Non-contacting
Measuring principle	Difference-Hall principle
Frequency range	0.2 20,000 Hz
Supply voltage	9 32 VDC or 2 x 9 32 VDC
Scanning object	Ferromagnetic materials Toothed wheel: Module m1 to m3; tooth face width > 7 mm (spur gear DIN867) Hole: $\emptyset \ge 5$ mm, web $\ge 2$ mm, depth $\ge 4$ mm Groove: $\ge 4$ mm, web $\ge 2$ mm, depth $\ge 4$ mm
Protection class	Housing: IP66/IP68 Connection: IP66/IP68
Material	Sensor tube: Stainless steel Adapter: Chromatised aluminium
Length	See customer drawing
Mounting	Flange mounting
Measuring channels	2 measuring channels or 2 galvanically iso- lated measuring channels or 2 measuring channels and 1 additional channel for rota- tion direction detection
Output signal and signal type	2 square wave signals or 2 square wave signals, 1 status signal
Output stage	Push-pull amplifier
Options	Inverted output signals; galvanically isolated output signals; status signal for direction of rotation detection



# Drehzahlsensor FA5

# **Application range**

Series FA[..]5 speed sensors are mainly used in the following areas: Transport technology. With a sensor tube made of stainless steel and a flange made of chrome-plated aluminium, the FA[. . ]5 is very robust. Our speed sensor type FA[. . ]52 made entirely of stainless steel is suitable for areas with a particularly high risk of corrosion.

The speed sensor measures the speed of ferromagnetic toothed wheels. Furthermore, they can be used for detecting movements of any ferromagnetic parts, e.g.:

- Toothed wheels with different tooth forms
- Bolt heads
- Lands detects holes, openings or grooves
- Impulse bands for plain shafts (accessories)

# **Specific features**

(E

- Excellent vibration and shock resistance
- Robust and high quality housing: IP68 pressure-tight and individually tested at 5 bar (for details see technical data)
- Connection outlet straight or lateral; with protective tubing on request
- High degree of EMC immunity for difficult electrical environment
- Detection of very low speed (near zero speed)
- Due to its design and type approval according to DIN EN 50155 especially suitable for transport technology

# **Measuring principle**

Series FA[..]5 speed sensors operate according to the difference-hall-effect principle.

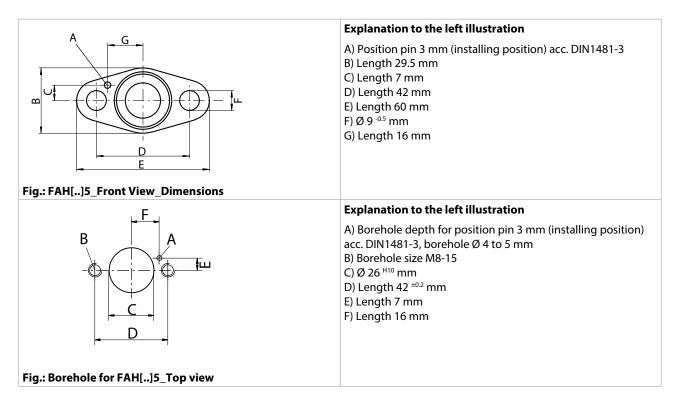
Two closely spaced Hall elements are located on the sensor chip. The field of a magnet generates a constant voltage in the Hall elements. Ferromagnetic objects with an interrupted surface as they pass the Hall elements cause the Hall voltage to change. When the moving object covers only one Hall element, a differential voltage is generated to provide a measuring signal. The frequency of this measuring signal is proportional to the speed of movement (rotational speed). The difference-Hall principle is direction sensitive.

# **Overview speed sensors FA[..]5**

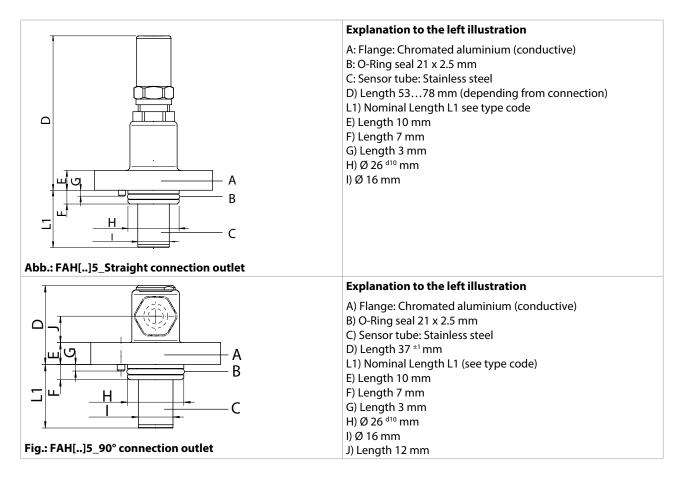
Туре	Measuring prin- ciple	Signal outputs	Signal form
FAHZ5	Difference-Hall	Two square wave signals, Q2 to Q1 is 90° phase shifted	$\begin{array}{c} Q1 \\ Q2 \\ 90^{\circ} \\ 90^{\circ} \\ \end{array}$
FAHS5	Difference-Hall	Two square wave signals, Q2 to Q1 is 90° phase shifted, one rotation direction signal	$\begin{array}{c} Q1 \\ Q2 \\ g0^{\circ} \\ s \end{array}$
FAHD5	Difference-Hall	Two square wave signals, galvanically isolated, Q2 to Q1 is 90° phase shifted	$\begin{array}{c} Q1 \\ - \cdot -$
FAHQ5	Difference-Hall	Two + Two inverted square wave signals, Q1 to Q2 and Q1_N to Q2_N are 90° phase shifted	$\begin{array}{c} Q1 \\ Q1_N \\ Q2 \\ Q2_N \\ 90^{\circ} \\ 90^{\circ} \\ \end{array}$

# Dimensions, connections and drawings

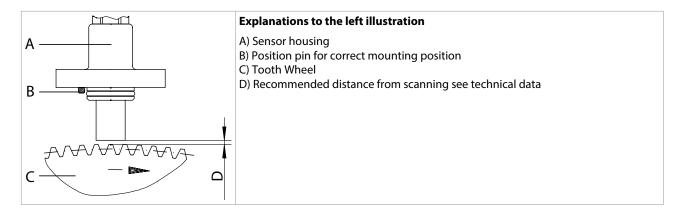
# Dimensions and mounting drawing



Recommended fixing: Hexagon socket screw DIN912 M8x20 with spring ring.



## Mounting position and scan object distance

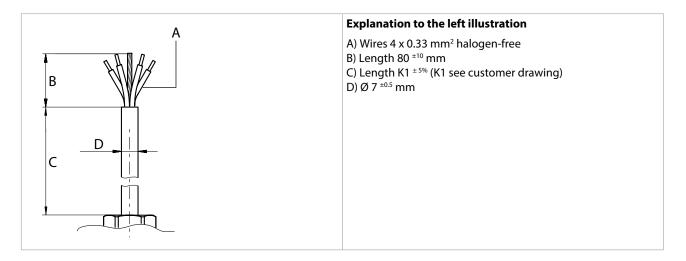


#### **Connection cables and pin assignment**

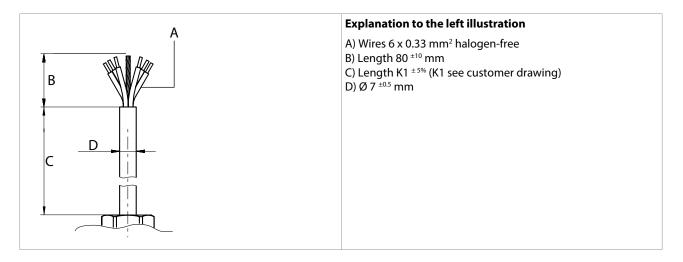
The following table shows an overview about the speed sensors and the related connection cables. All cables are available without protective tubing (-X type), with textile reinforced protective tubing (-XGT type), with steel reinforced protective tubing (-XGS type) or with polyamide protective tubing (-XP).

Connection type -X, -XGS, -XP	FAHZ5	FAHS5	FAHD5	FAHQ5
Cable with 4 wires	Х	-	-	-
Cable with 6 wires	-	Х	Х	Х

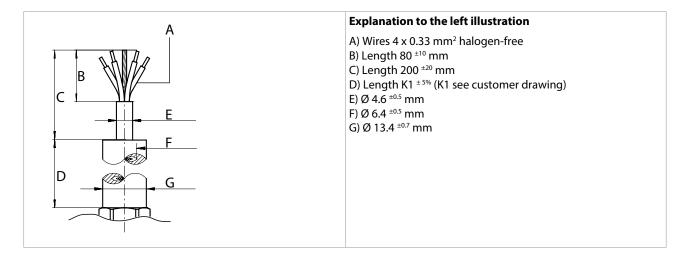
#### Connection cable type -X for sensors with 4 connecting wires



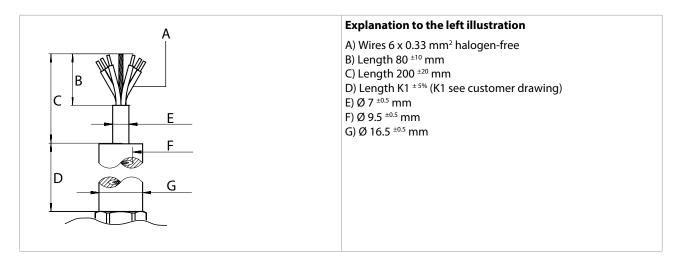
#### Connection cable type -X for sensors with 6 connecting wires



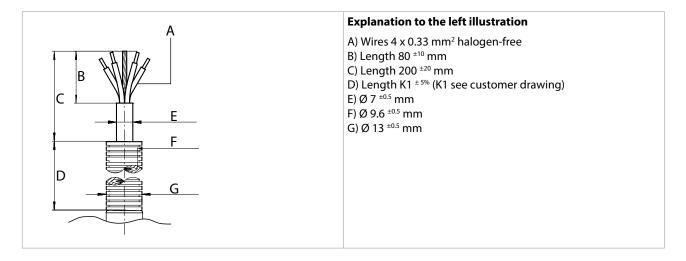
#### Connection cable type -XGS[..], -XGT[..] (protective tubing steel or textile reinforced) for sensors with 4 connecting wires



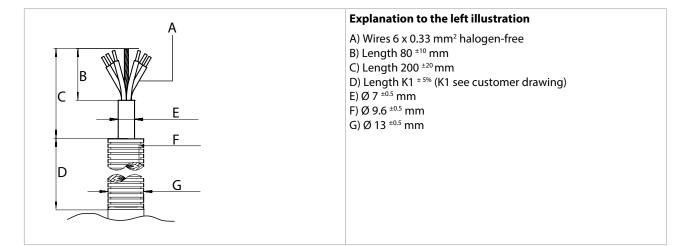
Connection cable type -XGS[..], -XGT[..] (protective tubing steel or textile reinforced) for sensors with 6 connecting wires



#### Connection cable type -XP[..] (polyamide protective tubing) for sensors with 4 connecting wires



#### Connection cable type -XP[..] (polyamide protective tubing) for sensors with 6 connecting wires



#### Connection assignment for type FA[..]Z

Colour	Explanation
Brown	U <sub>s</sub> +
Green	U <sub>s</sub> - (0V)
White	Signal Q1
Yellow	Signal Q2
Shield	Ground

#### Connection assignment for type FA[..]S

Colour	Explanation
Brown	U <sub>s</sub> +
Green	U <sub>s</sub> -(0V)
White	Signal Q1
Yellow	Signal Q2
Grey	Status output for direction of rotation detection
Pink	NC
Shield	Ground

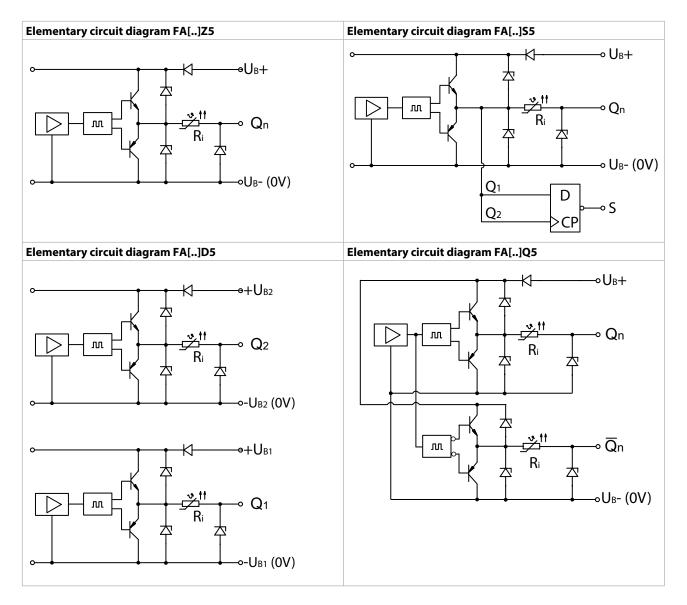
#### Connection assignment for type FA[..]D

Colour	Explanation
Brown	Sensor 1: U <sub>s1</sub> +
Green	Sensor 1: U <sub>S1</sub> - (0V)
White	Sensor 1: Signal Q1
Pink	Sensor 2: U <sub>s2</sub> +
Grey	Sensor 2: U <sub>s2</sub> - (0V)
Yellow	Sensor 2: Signal Q2
Shield	Ground

## Connection assignment for type FA[..]Q

Colour	Explanation
Brown	U <sub>s</sub> +
White	Q1
Grey	Q1_N, inverted to Q1
Yellow	Q2
Pink	Q2_N inverted to Q2
Green	U <sub>s</sub> - (0V)
Shield	Ground

## **Elementary circuit diagram**



# **General technical data**

Electrical connection		
Supply voltage	See specific technical data	
Nominal voltage	See specific technical data	
Current consumption	See specific technical data	
Reverse voltage protection	Yes	
Over voltage protection	Yes	
Connection	Cable end, customized connections acc. customer drawing	
Recommended cable length	< 100 m	
Used cable cross section	0.33 mm², shielded	

Electrical output	
Measuring channels	See specific technical data
Output signal and signal type	See specific technical data
Output stage	Push-pull amplifier
Continuous short circuit protection	Yes
Galvanic isolation	See specific technical data
Output level Low	Per output: ≤ 0.8 V @ 15 VDC, 10 mA, 24 °C
Output level High	Per output: ≥ UB-1.6 V @ 15 VDC, 10 mA, 24 °C
Output current NPN (Sink)	Per output: max50 mA
Output current PNP (Load)	Per output: max. 50 mA
Internal resistance Ri	See specific technical data
Rise time	≥ 10 V/µs

Signal acquisition		
Measuring principle	Difference-Hall principle	
Frequency range	0.2 20,000 Hz	
Scanning object - distance	0.2 3 mm; recommended: 1.0 ± 0.5 mm	
Scanning object	Ferromagnetic materials Toothed wheel: Module m1 to m3; tooth face width > 7 mm (spur gear DIN867) Hole: $\emptyset \ge 5$ mm, web $\ge 2$ mm, depth $\ge 4$ mm Groove: $\ge 4$ mm, web $\ge 2$ mm, depth $\ge 4$ mm	
Phase shift	90° ± 10% @ m1.5m3   90° ± 15% @ m1m1.25	
Duty cycle	50% ± 10%	

Environmental influences		
Operating temperature	-40 +120 °C	
Storage temperature	Recommended: -25 +70 °C; max.: -40 +105 °C (max. limit values within 30 days per year @ relative humidity 595%)	
Protection class	Housing: IP66/IP68 Connection: IP66/IP68	
Vibration resistance	DIN IEC 60068-T2-6, 10 g @ 52000 Hz (Sinus) DIN EN 61373, 30 g @ 20500 Hz (Random)	
Shock resistance	DIN IEC 60068-T2-27, 1000 m/s <sup>2</sup> @ 6 ms	
Climatic test	DIN IEC 60068-T2-1/-2/-30	
EMI - ESD	IEC 61000-4-2, Lev. 3	
EMI - Burst	IEC 61000-4-4, Lev. 3	
EMI - Surge	IEC 61000-4-5, Lev. 2	
EMI - HF immunity	IEC 61000-4-3, 10 V/m IEC 61000-4-6 (RF - conducted), 10 Veff IEC 60553 (AF - conducted), 10 Veff	
Emitted interference	CISPR 16-1, CISPR 16-2 EMC2	
Insulation voltage	500 VAC, 50 Hz @ 1 min	
Further standards	DIN EN 50155, DIN EN 45545	

Mechanical properties	
Material	Sensor tube: Stainless steel Adapter: Chromatised aluminium
Mounting	Flange mounting
Length	See customer drawing
Installation position	Preset with direction of rotation definition, with position pin defined
Weight	100 300 g (depending on connection and length)
Pressure resistance	5 bar (measuring area)

# Specific technical data

#### Technical data for electrical connection and output Sensors with two output signals (galvanically connected)

FAHZ[]				
Supply voltage	9 32 VDC			
Nominal voltage	15 VDC			
Current consumption	< 20 mA (without output current PNP)			
Internal resistance Ri	45 Ω			
Measuring channels	2 measuring channels			
Output signal and signal type	2 square wave signals			
Galvanic isolation	No			

## Sensors with two galvanically isolated output signals

FAHD[]	
Supply voltage	2 x 9 32 VDC
Nominal voltage	2 x 15 VDC
Current consumption	2 x <10 mA (without output current PNP)
Internal resistance Ri	50 Ω
Measuring channels	2 galvanically isolated measuring channels
Output signal and signal type	2 square wave signals
Galvanic isolation	Yes

#### Sensors with two output signals and status output

FAHS[]	
Supply voltage	9 32 VDC
Nominal voltage	15 VDC
Current consumption	< 20 mA (without output current PNP)
Internal resistance Ri	45 Ω
Measuring channels	2 measuring channels and 1 additional channel for rotation direction de- tection
Output signal and signal type	2 square wave signals, 1 status signal
Galvanic isolation	No

## Sensors with two output signals und two inverted output signals

FAHQ[]	
Supply voltage	9 32 VDC
Nominal voltage	15 VDC
Current consumption	< 20 mA (without output current PNP)
Internal resistance Ri	45 Ω
Measuring channels	2 measuring channels
Output signal and signal type	2 square wave signals not inverted, 2 square wave signals inverted
Galvanic isolation	No

# Type code

Type code structur	e										
FA	Н	Z	5-	11-	S	X	07-	M30-	<b>S</b> 0	Example: FAHZ5-11-SX07-M30S0	
	Meas	Measuring principle									
		Measuring principle supplement									
			Const	ructior	uction type and material						
				Nom	Nominal length L1 of the sensor tube						
			Connection outlet								
						Electr	ical co	nnection			
							Cable length				
								Modul	e		
									Shield	k	
Type code FA[]5											
Measuring principle	н	Differ	ence-H	all						ł	
Measuring principle		Z	2 output signals (voltage)								
supplement		D	2 out	2 output signals (voltage), galvanically isolated							
		S	-	2 output signals (voltage), guvuncury isolated 2 output signals (voltage) + Status output channel for direction of rotation detection							
		Q	-	-		oltage, 2		-		i i i i i i i i i i i i i i i i i i i	
Construction type and material			5-								
Nominal length	_			<b>11-</b> L1 = 29 mm							
Connection outlet					Without code: straight cable outlet					e outlet	
					S Lateral cable outlet						
Electrical connection					X Cable end standard (without protective tubing)						
						XGS Cable end, protective tubing, steel reinforced					
						XGT	Cable end, protective tubing, textile reinforced				
						ХР	Cable end, protective tubing, polyamide				
Sheath length							05-				
							07-	Sheath	n lengt	h 5.0 m, halogen-free 🕴 🕴	
							08-	08- Sheath length 7.5 m, halogen-free			
							09-	09- Sheath length 10.0 m, halogen-free			
Module								M10-	Мо	dule m1	
								M12-	Мо	dule m1.25	
							<b>M15-</b> Module m1.5		dule m1.5		
									Wit	hout code: Module m2	
								M25-	Module m2.5		
								M30-	Мо	dule m3	
Shield										Without code: Shield attached to the a sensor housing	
									<b>S</b> 0	Shield not attached to the sensor housing	
FA										Example: FAHZ5-11-X07 (Preferred type)	

# Special types

If our standard types do not correspond with your expectations, we are pleased to develop a special solution together with you.

# Preferred types

Features marked with a **\*** symbol at the end of the line are preferred features. If you select a preferred feature for each placeholder, the device is specified as preferred type. Preferred types are available quickly from stock. Other types will be delivered according to scheduled appointments.